



Inverter

Inverter i550-Cabinet

0.25 ... 132 kW

As easy as that.

Overview

Hardware overview of the inverter

PE connection

X100 Mains connection/DC bus

X9 Relay output

X2xx Network

Network status LEDs

X20 Memory module

X16 Interface
Diagnostic module

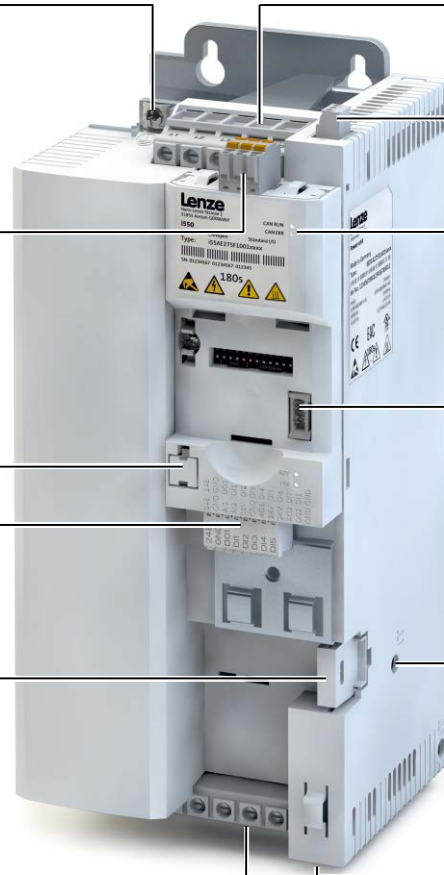
X3 Control terminals

X1 Safety module

IT-screws

X105 Motor connection

X109 PTC input



Content

| | | | | | |
|----------|---|-----------|-----------|--|-----------|
| 1 | General information | 4 | 7 | Commissioning | 18 |
| 1.1 | Target group..... | 4 | 7.1 | Keypad module | 18 |
| 1.2 | Application as directed | 4 | 7.1.1 | Functions of the keys..... | 19 |
| 1.3 | Device-specific standards and directives | 4 | 7.1.2 | Example of the keypad handling | 19 |
| 1.4 | Relevant standards and directives for the operator..... | 4 | 7.1.3 | Quick commissioning - terminal control..... | 19 |
| 1.5 | Identification of the products | 5 | 7.1.4 | Extended terminal control..... | 20 |
| 2 | Safety instructions | 5 | 7.2 | Keypad control | 20 |
| 2.1 | Basic safety measures | 5 | 7.3 | Commissioning with the EASY Starter..... | 20 |
| 2.2 | Layout of warning notices..... | 6 | 7.4 | The most important parameters at a glance..... | 21 |
| 2.3 | Residual hazards | 6 | 7.4.1 | Group 0: Favorites | 21 |
| 3 | Technical data | 7 | 7.4.2 | Group 2: Basic setting..... | 26 |
| 3.1 | Standards and operating conditions | 7 | 7.4.3 | Group 3: Motor control | 26 |
| 3.2 | Connection to the IT system | 7 | 7.4.4 | Group 7: Additional functions | 26 |
| 4 | Mechanical installation | 8 | 8 | Troubleshooting | 27 |
| 4.1 | Dimensions and assembly..... | 8 | 8.1 | Error message | 27 |
| 5 | Electrical installation | 9 | 8.2 | Reset error | 27 |
| 5.1 | General overview of the connections | 9 | 8.3 | Error codes..... | 28 |
| 5.2 | EMC-compliant installation..... | 9 | 8.4 | LED status..... | 30 |
| 5.3 | Control terminals | 10 | 9 | Further documents | 30 |
| 5.4 | Relay output..... | 10 | 10 | Disposal | 30 |
| 5.5 | PTC input..... | 10 | 11 | Glossary | 30 |
| 5.6 | 1-phase mains connection 120 V..... | 11 | | | |
| 5.7 | 1-phase mains connection 230/240 V | 12 | | | |
| 5.8 | 3-phase mains connection 230/240 V | 13 | | | |
| 5.9 | 3-phase mains connection 400 V..... | 14 | | | |
| 5.10 | 3-phase mains connection 480 V..... | 16 | | | |
| 6 | Initial switch-on | 18 | | | |

1 General information

Please read this documentation carefully before installing the inverter and observe the safety instructions!

This document only includes the most frequently asked questions and presents them in a simplified form for a better overview. Detailed technical and functional explanations can be found in the comprehensive product documentation.

The complete documentation, further information and tools regarding Lenze products can be found on the Internet: <http://www.Lenze.com>

1.1 Target group

Work on the product must only be carried out by qualified personnel. The personnel must be qualified in accordance with the IEC 60364 or CENELEC HD 384. Qualified personnel are persons who have the following knowledge and experience:

- They are familiar with the installation, mounting, commissioning, and operation of electrical and electronic modules.
- They have the corresponding qualifications for their work.
- They know and can apply all regulations for the prevention of accidents, directives, and laws applicable at the place of use.

1.2 Application as directed

The product is designed for the installation into electrical systems or machinery.

The i500 product family is designed for the power range of 0.25 ... 132 kW. The inverter i550 is suitable for conveyor and travelling drives, pumps, fans, winders, lifting systems and many other machine tasks. The inverter is not to be used as a household appliance, but for commercial or professional purposes only.

The inverter is not a machine in terms of the Machinery Directive.

1.3 Device-specific standards and directives

- The product meets the protection requirements of the Low-Voltage Directive 2014/35/EU.
- The harmonized standard EN 61800-5-1 is used for the inverters.

1.4 Relevant standards and directives for the operator

Application as directed

- If the product is used in accordance with the technical data, the drive systems comply with the EN 61800-3 categories.
- The inverter may only be used commercially or professionally as defined by EN 61000-3-2.
- The test voltage for insulation resistance tests between a control potential of 24 V and PE must be measured in accordance with EN 61800-5-1.
- The cables must be installed in accordance with EN 60204-1 or US National Electrical Code NFPA 70 / Canadian Electrical Code C22.1.

Commissioning

- Commissioning or starting the operation as directed of a machine with the product is prohibited until it has been ensured that the machine meets the regulations of the Machinery Directive (2006/42/EC) and the standard EN 60204-1.
- Commissioning or starting the operation as directed is only permissible if the EMC Directive 2014/30/EU is complied with.

1.5 Identification of the products

| | | I | 5 | 5 | A | E | xxx | x | 1 | x | x | x | x | xxxx |
|--|--|---|---|---|---|---|-----|---|---|---|---|---|---|------|
| Product type | Inverter | I | | | | | | | | | | | | |
| Product family | i500 | | 5 | | | | | | | | | | | |
| Product | i550 | | | 5 | | | | | | | | | | |
| Product generation | Generation 1 | | | | A | | | | | | | | | |
| Mounting type | Control cabinet mounting | | | | | E | | | | | | | | |
| Rated power [hp] (examples) | 0.33 hp | | | | | | 125 | | | | | | | |
| | 10 hp | | | | | | 275 | | | | | | | |
| | 125 hp | | | | | | 390 | | | | | | | |
| | 150 hp | | | | | | 411 | | | | | | | |
| Mains voltage and connection type (examples) | 1/N/PE AC 120 V | | | | | | | A | | | | | | |
| | 3/PE AC 230/240 V | | | | | | | B | | | | | | |
| Motor connections | Single axis | | | | | | | | 1 | | | | | |
| Integrated functional safety | Without safety function | | | | | | | | | 0 | | | | |
| | Basic Safety STO | | | | | | | | | A | | | | |
| Degree of protection | IP20, coated | | | | | | | | | | V | | | |
| Interference suppres- sion | Without | | | | | | | | | | | 0 | | |
| | Integrated RFI filter | | | | | | | | | | | 1 | | |
| Application | Default parameter setting: Region US (60-Hz networks) | | | | | | | | | | | | 1 | |
| Design types (examples) | Standard I/O without network | | | | | | | | | | | | | 000S |
| | Application I/O without network | | | | | | | | | | | | | 001S |

2 Safety instructions

2.1 Basic safety measures

Disregarding the following basic safety measures may lead to severe personal injury and damage to property!

- The product:
 - must only be used as directed.
 - must never be commissioned if they display signs of damage.
 - must never be technically modified.
 - must never be commissioned if they are not fully mounted.
 - must never be operated without required covers.
 - must only be disconnected from the installation in de-energized condition.
- Connect/disconnect all pluggable terminals only in de-energized condition.
- Carry out insulation resistance tests between 24-V control potential terminals and PE. The maximum test voltage must not exceed 110 V DC.

The safety measures are the condition for safe and trouble-free operation and the achievement of the specified product features.

The procedural notes and circuit details given in this document are suggestions and their transferability to the respective application has to be checked. The manufacturer does not take responsibility for the suitability of the process and circuit proposals.

The product may cause EMC interferences. The operator is responsible for executing the interference suppression measures.

2.2 Layout of warning notices

Safety instructions protect against injury to persons or damage to property. The measures described for the prevention of hazards must be complied with.



DANGER

Indicates an extremely hazardous situation. Failure to comply with this instruction will result in severe irreparable injury and even death.



WARNING

Indicates an extremely hazardous situation. Failure to comply with this instruction may result in severe irreparable injury and even death.



CAUTION

Indicates a hazardous situation. Failure to comply with this instruction may result in slight to medium injury.

NOTE

Indicates a material hazard. Failure to comply with this instruction may result in material damage.





2.3 Residual hazards

The user must take the residual hazards mentioned into consideration in the risk assessment for his/her machine/system.

If the above is disregarded, this may result in injuries to persons and material damage!

Product

Observe the warning labels on the product!

| Icon | Description |
|--|---|
|  | Electrostatic charge Before working on the product, the staff must ensure to be free of electrostatic charge. |
|  | Electrical voltage Before working on the product, check if no voltage is applied to the power terminals! After mains disconnection, the power terminals carry the hazardous electrical voltage given on the product! |
|  | High leakage current Implement fixed installation and PE connection! |
|  | Hot surface Use personal protective equipment or wait until the device has cooled down! |

Motor

In the event of a short circuit of two power transistors, a residual movement of up to 180°/ number of pole pairs on the motor may occur (e.g. 4-pole motor): residual movement max. $180^\circ/2 = 90^\circ$).

3 Technical data

3.1 Standards and operating conditions

| | | |
|--|-------------|--|
| Conformities | CE | 2014/35/EU, 2014/30/EU |
| | EAC | TR TC 004/2011, TP TC 020/2011 |
| | RoHS 2 | 2011/65/EU |
| Approvals | CULUS | UL 61800-5-1, CSA 22.2 No. 274 |
| Energy efficiency | Class IE2 | EN 50598-2 |
| Degree of protection | IP20 | EN 60529 (except in wire range of terminals) |
| | | NEMA 250 (type 1 protection against accidental contact only) |
| | Open type | Only in UL-approved systems |
| Power systems | TT, TN | Voltage against earth: max. 300 V |
| | IT | Apply the measures described for IT systems! |
| Mains switching | | 3 x within one minute possible |
| Operation with residual current circuit breaker (optional) (120-V network and 230-V network) | | Up to 4 kW 30 mA, above this 300 mA |
| | | Up to 4 kW 30 mA, above this 300 mA |
| Cable length without EMC category | | max. 100 m (≤ 5.5 kW max. 50 m) |
| | | |
| Cable length for EMC | Category C2 | max. 20 m (≤0.37 kW max. 15 m) |
| | Category C3 | max. 35 m (≤0.37 kW max. 15 m) |
| Switching frequencies | | 2, 4, 8, 16 kHz. The rated output currents apply at 45 °C and switching frequencies of 2 and 4 kHz, and at 40 °C and switching frequencies of 8 and 16 kHz |
| Ambient temperature | | 55 °C (derating of 2.5 %/ °C above 45 °C) |
| Max. output frequency | | 0 Hz ... 599 Hz |
| Overload capacity (120-V network and 230-V network) | | 200 % for 3 s; 150 % for 60 s |
| Overload capacity (400-V network) | | 200 % for 3 s; Heavy Duty: 150 % for 60 s; Light Duty: 125 % for 60 s |

3.2 Connection to the IT system

NOTE

Electrical voltage

Internal components have earth/ground potential if the IT screws are not removed.

The monitoring devices of the IT system will be triggered.

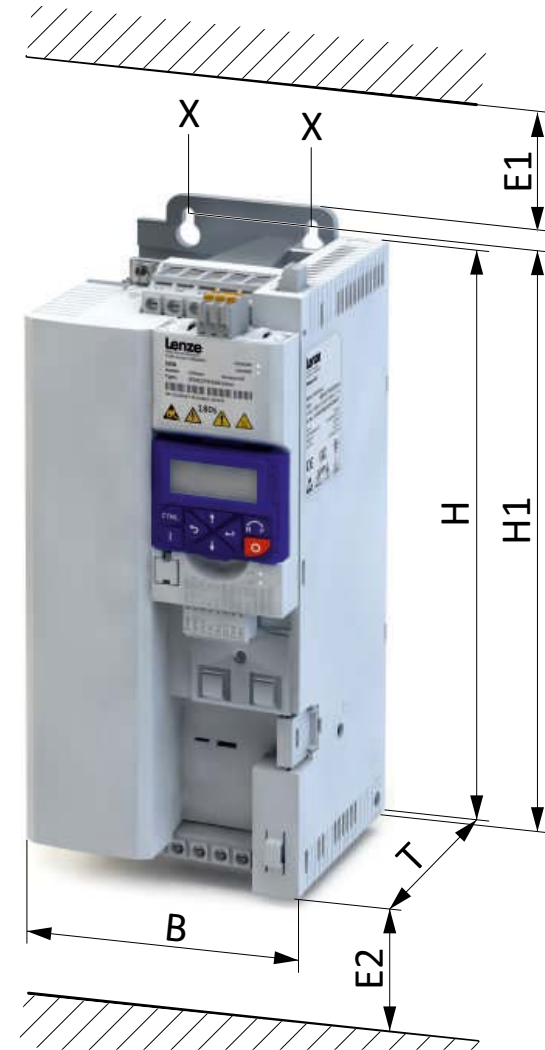
► Before connection to an IT system be absolutely sure to remove the IT screws.



4 Mechanical installation

4.1 Dimensions and assembly

| | Rated power [kW] | Weight [kg] | H [mm] | B [mm] | T [mm] | H1 [mm] | X/Y [screws + hole spacing] | | E1 [mm] | E2 [mm] | |
|--|------------------|-------------|--------|--------|--------|---------|-----------------------------|-----|---------|---------|-----|
| 1-phase mains connection 120 V; without integrated RFI filter | | | | | | | | | | | |
| I55AExxxA | 0.25 ... 0.37 | 1 | 180 | 60 | 130 | 190 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxA | 0.75 ... 1.1 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| 1-phase mains connection 230/240 V; with integrated RFI filter | | | | | | | | | | | |
| I55AExxxB | 0.25 ... 0.37 | 0.8 | 155 | 60 | 130 | 165 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxB | 0.55 ... 0.75 | 1 | 180 | 60 | 130 | 190 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxB | 1.1 ... 2.2 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| 1-/3-phase mains connection 230/240 V; without integrated RFI filter | | | | | | | | | | | |
| I55AExxxD | 0.25 ... 0.37 | 0.8 | 155 | 60 | 130 | 165 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxD | 0.55 ... 0.75 | 1 | 180 | 60 | 130 | 190 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxD | 1.1 ... 2.2 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxC | 4 ... 5.5 | 2.1 | 250 | 90 | 130 | 260 | 1/1 | - | M5 | 50 | 100 |
| 3-phase mains connection 400 V ... Heavy Duty; with integrated RFI filter | | | | | | | | | | | |
| I55AExxxF | 0.37 | 0.8 | 155 | 60 | 130 | 165 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxF | 0.55 ... 0.75 | 1 | 180 | 60 | 130 | 190 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxF | 1.1 ... 2.2 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxF | 3 ... 5.5 | 2.1 | 250 | 90 | 130 | 260 | 2/2 | 30 | M5 | 50 | 100 |
| I55BExxxF | 3 ... 4 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxF | 7.5 ... 11 | 3.7 | 276 | 120 | 130 | 285 | 2/2 | 60 | M5 | 50 | 100 |
| I55AExxxF | 15 ... 22 | 10.3 | 347 | 204.5 | 222 | 343 | 2/2 | 180 | M6 | 50 | 100 |
| I55AExxxF | 30 ... 45 | 17.2 | 450 | 250 | 230 | 496 | 2/2 | 210 | M8 | 95 | 120 |
| I55AExxxF | 55 ... 75 | 24 | 536 | 250 | 265 | 596 | 2/2 | 210 | M8 | 95 | 260 |
| I55AExxxF | 90 ... 110 | 35.6 | 685 | 258 | 304 | 748 | 2/2 | 210 | M8 | 95 | 260 |
| 3-phase mains connection 400 V - Light Duty; with integrated RFI filter | | | | | | | | | | | |
| I55AExxxF | 4 ... 7.5 | 2.3 | 250 | 90 | 130 | 260 | 2/2 | 30 | M5 | 50 | 100 |
| I55BExxxF | 3 ... 4 | 1.35 | 250 | 60 | 130 | 260 | 1/1 | - | M5 | 50 | 50 |
| I55AExxxF | 11 ... 15 | 3.7 | 276 | 120 | 130 | 285 | 2/2 | 60 | M5 | 50 | 100 |
| I55AExxxF | 18.5 ... 30 | 10.3 | 347 | 204.5 | 222 | 343 | 2/2 | 180 | M6 | 50 | 100 |
| I55AExxxF | 37 ... 55 | 17.2 | 450 | 250 | 230 | 496 | 2/2 | 210 | M8 | 95 | 120 |
| I55AExxxF | 75 ... 90 | 24 | 536 | 250 | 265 | 596 | 2/2 | 210 | M8 | 95 | 260 |
| I55AExxxF | 110 ... 132 | 35.6 | 685 | 258 | 304 | 748 | 2/2 | 210 | M8 | 95 | 260 |



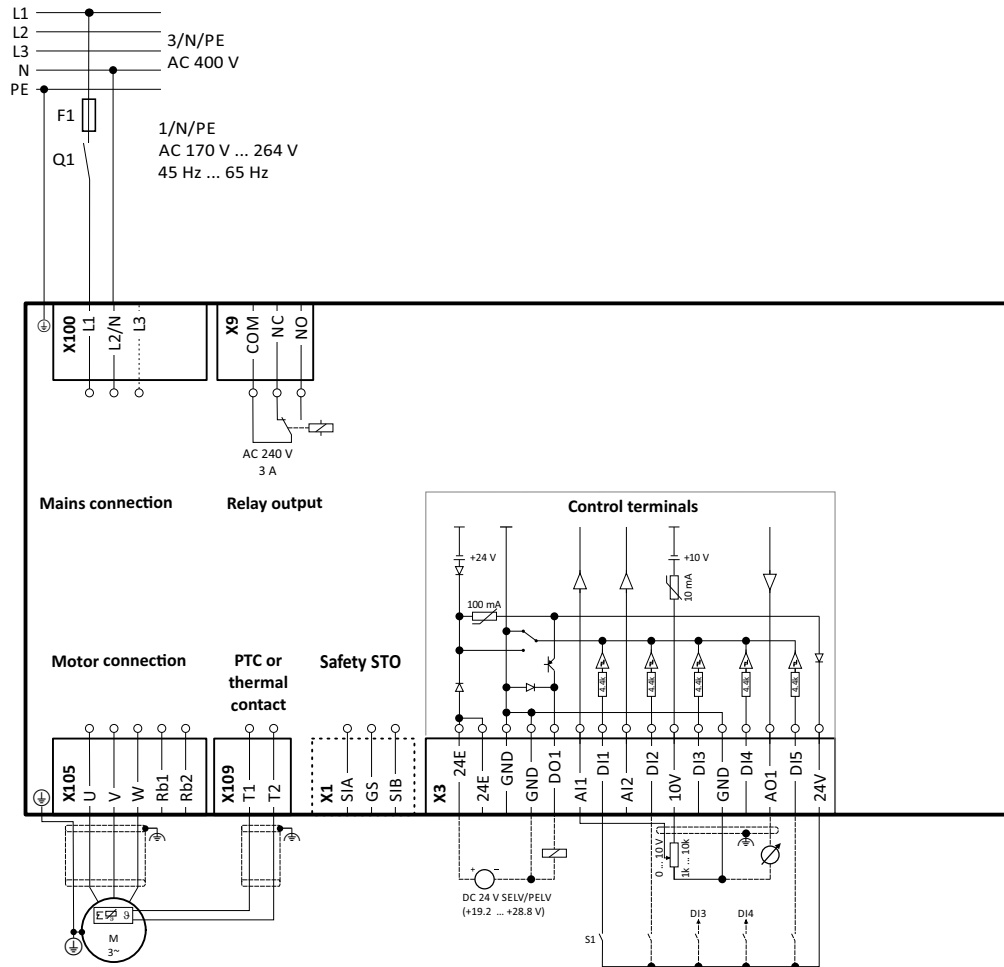
H: Device height
 B: Device width
 T: Device depth
 H1: Hole dimension for top/bottom fixing

X/Y: Number of top/bottom fixings
 (Y not visible in the illustration)
 X - X: Hole spacing over center of device
 E1: Top mounting clearance
 E2: Bottom mounting clearance

5 Electrical installation

5.1 General overview of the connections

The connection diagram is considered exemplary for all voltage and power classes. Deviating mains connection diagrams can be found in the corresponding chapters.



5.2 EMC-compliant installation

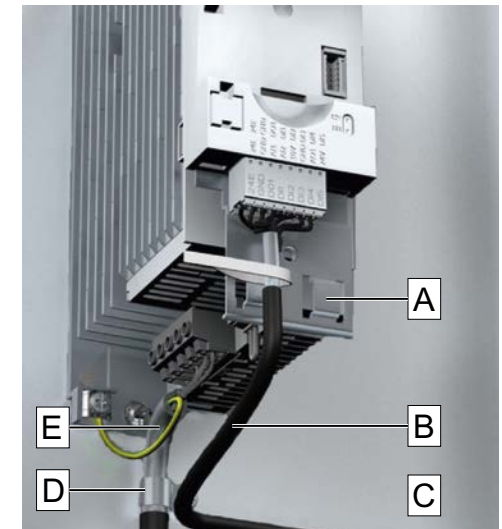
The drive system (inverter and drive) meet the EMC Directive 2014/30/EU if they are installed according to the guidelines of CE-typical drive systems.

The structure in the control cabinet must support the EMC-compliant installation with shielded motor cables.

- Please use sufficiently conductive shield connections.
- Connect the housing with shielding effect to the grounded mounting plate with a surface as large as possible, e. g. of inverters and RFI filters.
- Use central earthing points.

The following figure shows an effective wiring with shielding on the control cabinet wall.

- A Shield connection for control connections
- B Control cable
- C Electrically conductive mounting plate
- D Shield clamps
- E Low-capacitance motor cable
(C-core/core/C-core/shield <math>< 75/150 \text{ pF/m} \le 2.5 \text{ mm}^2</math>;
C-core/core/C-core/shield <math>< 150/300 \text{ pF/m} \ge 4 \text{ mm}^2</math>)



Alternatively, the motor cable can be shielded on an optional motor shield plate.

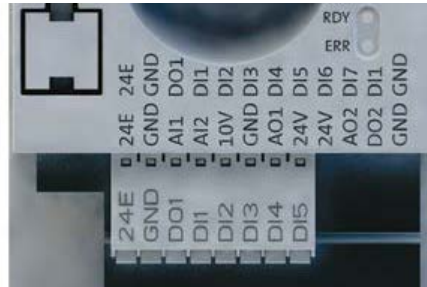
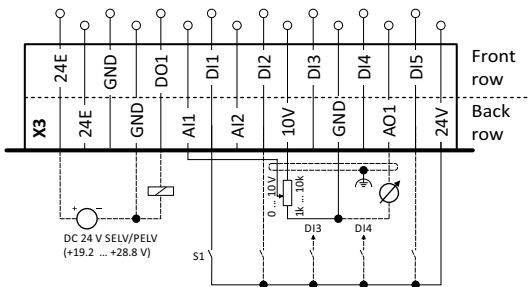
5.3 Control terminals

Standard I/O

| Input/output | Terminal X3 | Information |
|---------------------|---------------------------|--|
| Digital inputs | DI1, DI2, DI3, DI4, DI5 | DI3/DI4 can be optionally used as frequency or encoder input. HIGH-active/LOW-active switchable LOW = 0 ... +3 V, HIGH = +12 V ... +30 V |
| Digital outputs | DO1 | Digital output (max. 100 mA for DO1 and 24-V output) |
| Analog inputs | AI1, AI2 | Can be optionally used as voltage input or current input. |
| Analog outputs | AO1 | Can be optionally used as voltage output or current output. |
| 24-V input | 24E | Input for mains-independent power DC supply of control electronics (including communication). Max. 1 A |
| 10-V output | 10 V | Primarily for the supply of a potentiometer (1 ... 10 k Ω). Max. 10 mA |
| 24-V output | 24 V | Primarily for the supply of digital inputs. (Max. 100 mA for DO1 and 24-V output) |
| Reference potential | GND | |
| Connection system | Pluggable spring terminal | |

| Inverter | [kW] | 0.25 ... 132 |
|--------------------------|-----------------|---------------------------|
| Connection | | Control terminals X3 |
| Connection type | | Pluggable spring terminal |
| Min. cable cross-section | mm ² | - |
| Max. cable cross-section | mm ² | 1.5 |
| Stripping length | mm | 9 |
| Tightening torque | Nm | - |
| Tools required | | 0.4 x 2.5 |

Control terminals



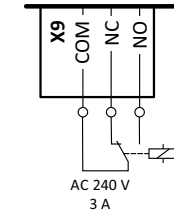
5.4 Relay output

The relay is not suitable for direct switching of an electromechanical holding brake.

Use a corresponding suppressor circuit in case of an inductive or capacitive load.

| Inverter | [kW] | 0.25 ... 132 |
|--|-----------------|--------------------------|
| Connection | | Relay output X9 |
| Connection type | | Pluggable screw terminal |
| Min. cable cross-section | mm ² | - |
| Max. cable cross-section | mm ² | 1.5 |
| Stripping length | mm | 6 |
| Tightening torque | Nm | 0.2 |
| Tools required | | 0.4 x 2.5 |
| | COM | Common contact |
| | NC | Normally-closed contact |
| | NO | Normally-open contact |
| Max. switching voltage/switching current | | AC 240 V/3 A |
| | | DC 24 V/2 A |
| | | DC 240 V/0.16 A |

Relay output



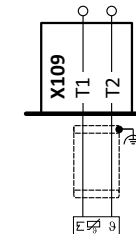
5.5 PTC input

In the default setting, the motor temperature monitoring is active! By default, a wire jumper is installed between the terminals T1 and T2.

Before connecting a thermal sensor, remove the wire jumper.

| Inverter | [kW] | 0.25 ... 132 |
|--------------|------|-----------------------------|
| Connection | | PTC or thermal contact X109 |
| | | Terminal X109: T1 |
| | | Terminal X109: T2 |
| Sensor types | | PTC single sensor |
| | | PTC triplet sensor |
| | | Thermal contact |

PTC input



5.6 1-phase mains connection 120 V

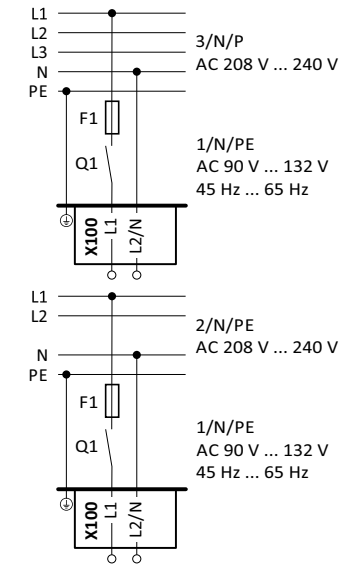
Terminal data, 1-phase 120 V

| Inverter | [kW] | I55AxxxA 0.25 ... 0.37 | I55AxxxA 0.75 ... 1.1 | I55AxxxA 0.25 ... 1.1 | I55AxxxA 0.25 ... 1.1 |
|--------------------------|-----------------|---------------------------|--------------------------|--------------------------|--------------------------|
| Connection | | Mains connection X100 | | PE connection | Motor connection X105 |
| Connection type | | Pluggable screw terminal | | PE screw | Pluggable screw terminal |
| Min. cable cross-section | mm ² | 1 | | 1.5 | 1 |
| Max. cable cross-section | mm ² | 2.5 | 6 | 6 | 2.5 |
| Stripping length | mm | 8 | | 10 | 8 |
| Tightening torque | Nm | 0.5 | 0.7 | 2 | 0.5 |
| Tools required | | 0.5 x 3.0 | 0.6 x 3.5 | Torx 20 | 0.5 x 3.0 |

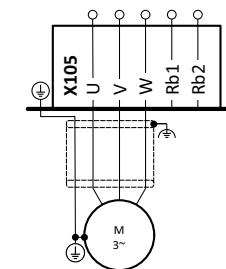
Fusing data

| Inverter | [kW] | 0.25 | 0.37 | 0.75 | 1.1 |
|--------------------------------------|------|-----------------|------|------|------|
| Rated output current (8 kHz) | A | 1.7 | 2.4 | 4.2 | 6 |
| Max. output current (15 s) | A | 2.6 | 3.6 | 6.3 | 9 |
| Operation without mains choke | | | | | |
| Rated mains current | A | 6.8 | 9.6 | 16.8 | 22.9 |
| Fuse | | | | | |
| Characteristic | | gG/gL or gRL | | | |
| Max. rated current | A | 16 | 16 | 25 | 25 |
| Circuit breaker | | | | | |
| Characteristic | | B | | | |
| Max. rated current | A | 16 | 16 | 25 | 25 |
| Earth-leakage circuit breaker | | | | | |
| 1-phase mains connection | | ≥ 30 mA, type B | | | |

Mains connection



Motor connection



5.7 1-phase mains connection 230/240 V

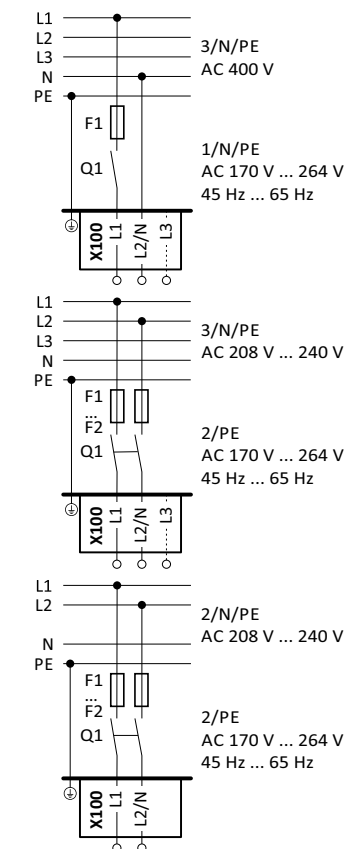
Terminal data, 1-phase 230/240 V

| Inverter | [kW] | I55AxxxB | I55AxxxA | I55AxxxA | I55AxxxA |
|--------------------------|-----------------|--------------------------|-----------|---------------|--------------------------|
| Connection | | Mains connection X100 | | PE connection | Motor connection X105 |
| Connection type | | Pluggable screw terminal | | PE screw | Pluggable screw terminal |
| Min. cable cross-section | mm ² | - | | - | - |
| Max. cable cross-section | mm ² | 2.5 | 6 | 6 | 2.5 |
| Stripping length | mm | 8 | | 10 | 8 |
| Tightening torque | Nm | 0.5 | 0.7 | 2 | 0.5 |
| Tools required | | 0.5 x 3.0 | 0.6 x 3.5 | Torx 20 | 0.5 x 3.0 |

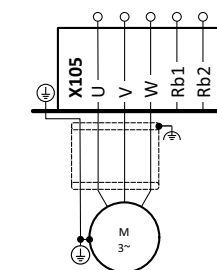
Fusing data

| Inverter | [kW] | 0.25 | 0.37 | 0.55 | 0.75 | 1.1 | 1.5 | 2.2 |
|--------------------------------------|------|-----------------|------|------|------|------|------|------|
| Rated output current (8 kHz) | A | 1.7 | 2.4 | 3.2 | 4.2 | 6 | 7 | 9.6 |
| Max. output current (15 s) | A | 2.6 | 3.6 | 4.8 | 6.3 | 9 | 10.5 | 14.4 |
| Operation without mains choke | | | | | | | | |
| Rated mains current | A | 4 | 5.7 | 7.6 | 10 | 14.3 | 16.7 | 22.5 |
| Fuse | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | | | | |
| Max. rated current | A | 10 | 10 | 16 | 16 | 25 | 25 | 25 |
| Circuit breaker | | | | | | | | |
| Characteristic | | B | | | | | | |
| Max. rated current | A | 10 | 10 | 16 | 16 | 25 | 25 | 25 |
| Earth-leakage circuit breaker | | | | | | | | |
| 1-phase mains connection | | ≥ 30 mA, type B | | | | | | |

Mains connection



Motor connection



5.8 3-phase mains connection 230/240 V

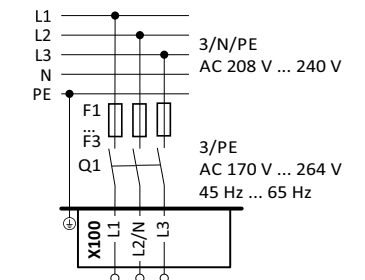
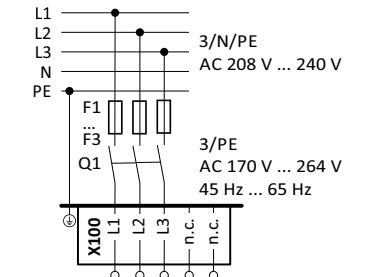
Terminal data, 3-phase 230/240 V

| Inverter | [kW] | I55AxxxD 0.25 ... 0.75 | I55AxxxD 1.1 ... 2.2 | I55AxxxC 4 ... 5.5 | I55AxxxX 0.25 ... 5.5 | I55AxxxD 0.25 ... 2.2 | I55AxxxC 4 ... 5.5 |
|--------------------------|-----------------|---------------------------|-------------------------|-----------------------|--------------------------|--------------------------|-----------------------|
| Connection | | Mains connection X100 | | | PE connection | Motor connection X105 | |
| Connection type | | Pluggable screw terminal | | Screw terminal | PE screw | Pluggable screw terminal | Screw terminal |
| Min. cable cross-section | mm ² | - | | | - | - | |
| Max. cable cross-section | mm ² | 2.5 | 6 | 6 | 6 | 2.5 | 6 |
| Stripping length | mm | 8 | | | 10 | 8 | |
| Tightening torque | Nm | 0.5 | 0.7 | 0.5 | 2 | 0.5 | 0.5 |
| Tools required | | 0.5 x 3.0 | | 0.6 x 3.5 | Torx 20 | 0.5 x 3.0 | |

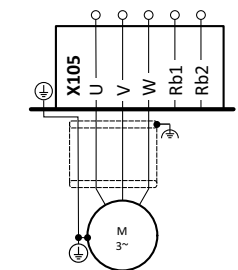
Fusing data

| Inverter | [kW] | 0.25 | 0.37 | 0.55 | 0.75 | 1.1 | 1.5 | 2.2 | 4 | 5.5 | |
|--|------|-----------------|------|------|------|-----|------|------|------|------------------|--|
| Rated output current (8 kHz) (Heavy Duty) | A | 1.7 | 2.4 | 3.2 | 4.2 | 6 | 7 | 9.6 | 16.5 | 23 | |
| Max. output current (15 s) | A | 2.6 | 3.6 | 4.8 | 6.3 | 9 | 10.5 | 14.4 | 24.8 | 34.5 | |
| Rated output current (Light Duty) | A | - | - | - | - | - | - | - | - | 20.6 | |
| Max. output current (15 s) | A | - | - | - | - | - | - | - | - | 24.8 | |
| Operation without mains choke | | | | | | | | | | | |
| Rated mains current | A | 2.6 | 3.9 | 4.8 | 6.4 | 7.8 | 9.5 | 13.6 | 20.6 | 28.8 | |
| Fuse | | | | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | |
| Circuit breaker | | | | | | | | | | | |
| Characteristic | | B | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | |
| Earth-leakage circuit breaker | | | | | | | | | | | |
| 3-phase mains connection | | ≥ 30 mA, type B | | | | | | | | ≥ 300 mA, type B | |

Mains connection



Motor connection



5.9 3-phase mains connection 400 V

Terminal data, 3-phase 400 V

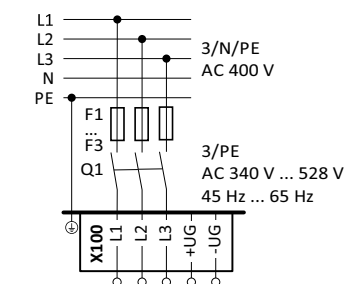
| Inverter | [kW] | I55AxxxF | I55BxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF |
|--------------------------|-----------------|--------------------------|----------|----------------|-----------|-----------|---------------|----------|----------|--------------------------|----------|----------------|-----------|-----------|
| Connection | | Mains connection X100 | | | | | PE connection | | | Motor connection X105 | | | | |
| Connection type | | Pluggable screw terminal | | Screw terminal | | | PE screw | | | Pluggable screw terminal | | Screw terminal | | |
| Min. cable cross-section | mm ² | 1 | | | | | 1.5 | | | 1 | | | | |
| Max. cable cross-section | mm ² | 2.5 | 4 | 6 | 16 | 35 | 6 | 16 | 25 | 2.5 | 6 | 16 | 35 | |
| Stripping length | mm | 8 | 8 | 9 | 11 | 18 | 10 | 11 | 16 | 8 | 9 | 11 | 18 | |
| Tightening torque | Nm | 0.5 | 0.6 | 0.5 | 1.2 | 3.8 | 2 | 3.4 | 4 | 0.5 | 0.5 | 1.2 | 3.8 | |
| Tools required | | 0.5 x 3.0 | | 0.6 x 3.5 | 0.6 x 4.0 | 0.6 x 5.5 | Torx 20 | PZ2 | PZ2 | 0.5 x 3.0 | | 0.6 x 3.5 | 0.8 x 4.0 | 0.8 x 5.5 |

Fusing data/performance data

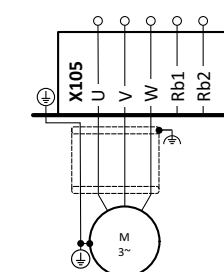
| Inverter | [kW] | 0.37 | 0.55 | 0.75 | 1.1 | 1.5 | 2.2 | 3 | 4 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | |
|---|------|-----------------|------|------|-----|-----|------------------|-----|------|------|------|------|------|------|----|--|
| Rated output current (8 kHz) (Heavy Duty) | A | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.6 | 7.3 | 9.5 | 13 | 16.5 | 23.3 | 32 | 40 | 47 | |
| Max. output current (15 s) | A | 2 | 2.7 | 3.6 | 4.8 | 5.9 | 8.4 | 11 | 14.3 | 19.5 | 25 | 35 | 48 | 60 | 71 | |
| Rated output current (Light Duty) | A | - | - | - | - | - | - | - | 8.8 | 11.9 | 15.6 | 23 | 28.2 | 38.4 | 48 | |
| Max. output current (15 s) | A | - | - | - | - | - | - | - | 11 | 14.3 | 19.5 | 23.6 | 35 | 48 | 60 | |
| Operation without mains choke | | | | | | | | | | | | | | | | |
| Rated mains current | A | 1.8 | 2.5 | 3.3 | 4.4 | 5.4 | 7.8 | 9.6 | 12.5 | 17.2 | 20 | 28.4 | 38.7 | 48.4 | - | |
| Fuse | | gG/gL or gRL | | | | | | | | | | | | | | |
| Characteristic | | | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | - | |
| Circuit breaker | | B | | | | | | | | | | | | | | |
| Characteristic | | | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | - | |
| Operation with mains choke | | | | | | | | | | | | | | | | |
| Rated mains current | A | 1.4 | 2 | 2.6 | 3 | 3.7 | 5.3 | 6.9 | 9 | 12.4 | 15.7 | 22.3 | 28.8 | 36 | 42 | |
| Fuse | | gG/gL or gRL | | | | | | | | | | | | | | |
| Characteristic | | | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Circuit breaker | | B | | | | | | | | | | | | | | |
| Characteristic | | | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Earth-leakage circuit breaker | | ≥ 30 mA, type B | | | | | | | | | | | | | | |
| 3-phase mains connection | | ≥ 30 mA, type B | | | | | ≥ 300 mA, type B | | | | | | | | | |

In case of Light Duty above 15 kW and Heavy Duty above 22 kW, a mains choke must be used.

Mains connection



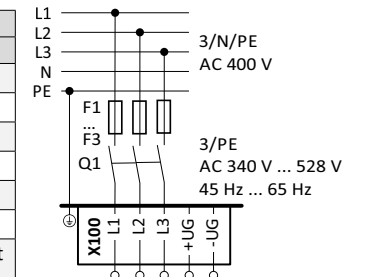
Motor connection



Terminal data, 3-phase 400 V

| | | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF |
|--------------------------|-----------------|-----------------------|---------------------|---------------------|------------------|-------------------|-----------------------|---------------------|---------------------|
| Inverter | [kW] | 30 ... 45 | 55 ... 75 | 90 ... 132 | 30 ... 75 | 90 ... 132 | 30 ... 45 | 55 ... 75 | 90 ... 132 |
| Connection | | Mains connection X100 | | | PE connection | | Motor connection X105 | | |
| Connection type | | Screw terminal | | | PE screw | PE bolt | Screw terminal | | |
| Min. cable cross-section | mm ² | 1 | | | 1.5 | | 1 | | |
| Max. cable cross-section | mm ² | 50 | 95 | 150 | 25 | 150 | 50 | 95 | 150 |
| Stripping length | mm | 19 | 22 | 28 | 16 | - | 19 | 22 | 28 |
| Tightening torque | Nm | 4 | 10 | 18 | 4 | 10 | 4 | 10 | 18 |
| Tools required | | Hexagon socket 5 | Hexagon socket 6 | Hexagon socket 8 | PZ2 | Wrench size 13 | Hexagon socket 5 | Hexagon socket 6 | Hexagon socket 8 |

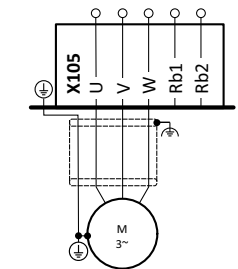
Mains connection



Fusing data

| Inverter | [kW] | 30 | 37 | 45 | 55 | 75 | 90 | 110 | 132 |
|--------------------------------------|-------------|------------------|-----------|-----------|-----------|-----------|-----------|------------|------------|
| Rated output current (Heavy Duty) | A | 61 | 76 | 89 | 110 | 150 | 180 | 212 | - |
| Max. output current (15 s) | A | 92 | 114 | 134 | 165 | 225 | 270 | 318 | - |
| Rated output current (Light Duty) | A | 56.4 | 73.2 | 91.2 | 107 | 132 | 180 | 216 | 254 |
| Max. output current (15 s) | A | 71 | 92 | 114 | 135 | 165 | 225 | 270 | 318 |
| Operation with mains choke | | | | | | | | | |
| Rated mains current | A | 54.9 | 68 | 80 | 99 | 135 | 168 | 198 | - |
| Fuse | | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | gR | | | | |
| Max. rated current | A | 80 | 100 | 125 | 160 | 16 | 300 | 300 | 300 |
| Circuit breaker | | | | | | | | | |
| Characteristic | | B | | | | | | | |
| Max. rated current | A | 80 | 100 | 125 | - | - | - | - | - |
| Earth-leakage circuit breaker | | | | | | | | | |
| 3-phase mains connection | | ≥ 300 mA, type B | | | | | | | |

Motor connection



In case of Light Duty above 15 kW and Heavy Duty above 22 kW, a mains choke must be used.

5.10 3-phase mains connection 480 V

Terminal data, 3-phase 480 V

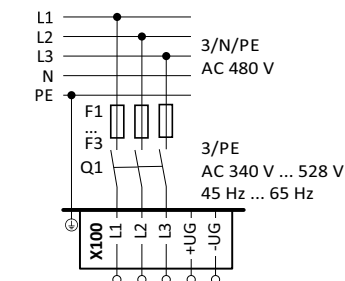
| Inverter | [kW] | I55AxxxF | I55BxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF | I55AxxxF |
|--------------------------|-----------------|--------------------------|-----------|----------------|-----------|-----------|---------------|----------|----------|--------------------------|-----------|----------------|-----------|-----------|
| Connection | | Mains connection X100 | | | | | PE connection | | | Motor connection X105 | | | | |
| Connection type | | Pluggable screw terminal | | Screw terminal | | | PE screw | | | Pluggable screw terminal | | Screw terminal | | |
| Min. cable cross-section | mm ² | 1 | | | | | 1.5 | | | 1 | | | | |
| Max. cable cross-section | mm ² | 2.5 | 4 | 6 | 16 | 35 | 6 | 16 | 25 | 2.5 | 2.5 | 6 | 16 | 35 |
| Stripping length | mm | 8 | 8 | 9 | 11 | 18 | 10 | 11 | 16 | 8 | 8 | 9 | 11 | 18 |
| Tightening torque | Nm | 0.5 | 0.6 | 0.5 | 1.2 | 3.8 | 2 | 3.4 | 4 | 0.5 | 0.5 | 0.5 | 1.2 | 3.8 |
| Tools required | | 0.5 x 3.0 | 0.5 x 3.0 | 0.6 x 3.5 | 0.8 x 4.0 | 0.8 x 5.5 | Torx key 20 | PZ2 | | 0.5 x 3.0 | 0.5 x 3.0 | 0.6 x 3.5 | 0.8 x 4.0 | 0.8 x 5.5 |

Fusing data/performance data

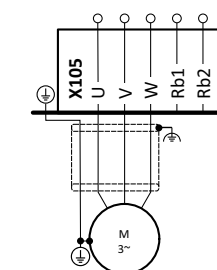
| Inverter | [kW] | 0.37 | 0.55 | 0.75 | 1.1 | 1.5 | 2.2 | 3 | 4 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | |
|---|------|-----------------|------|------|-----|-----|-----|-----|------|------|------------------|------|------|------|------|--|
| Rated output current (8 kHz) (Heavy Duty) | A | 1.1 | 1.6 | 2.1 | 3 | 3.5 | 4.8 | 6.3 | 8.2 | 11 | 14 | 21 | 27 | 34 | 40.4 | |
| Max. output current (15 s) | A | 1.7 | 2.4 | 3.2 | 4.5 | 5.3 | 7.2 | 9.5 | 12.3 | 16.5 | 21 | 31.5 | 40.5 | 51 | 61 | |
| Rated output current (Light Duty) | A | - | - | - | - | - | - | - | 7.6 | 9.8 | 13.2 | 18.3 | 25.2 | 32.4 | 40.8 | |
| Max. output current (15 s) | A | - | - | - | - | - | - | - | 9.5 | 12.3 | 16.5 | 21 | 31.5 | 40.5 | 51 | |
| Operation without mains choke | | | | | | | | | | | | | | | | |
| Rated mains current | A | 1.5 | 2.1 | 2.8 | 3.7 | 4.5 | 6.5 | 8 | 10.5 | 14.3 | 16.6 | 23.7 | 32.3 | 40.3 | 47.4 | |
| Fuse | | | | | | | | | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Circuit breaker | | | | | | | | | | | | | | | | |
| Characteristic | | B | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Operation with mains choke | | | | | | | | | | | | | | | | |
| Rated mains current | A | 1.2 | 1.7 | 2.2 | 2.5 | 3.1 | 4.4 | 5.8 | 7.5 | 10.3 | 13.1 | 18.6 | 24 | 30 | 35.3 | |
| Fuse | | | | | | | | | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Circuit breaker | | | | | | | | | | | | | | | | |
| Characteristic | | gG/gL or gRL | | | | | | | | | | | | | | |
| Max. rated current | A | 10 | 10 | 10 | 16 | 16 | 16 | 25 | 25 | 25 | 32 | 32 | 63 | 63 | 63 | |
| Earth-leakage circuit breaker | | | | | | | | | | | | | | | | |
| 3-phase mains connection | | ≥ 30 mA, type B | | | | | | | | | ≥ 300 mA, type B | | | | | |

In case of Light Duty above 15 kW and Heavy Duty above 30 kW, a mains choke must be used.

Mains connection



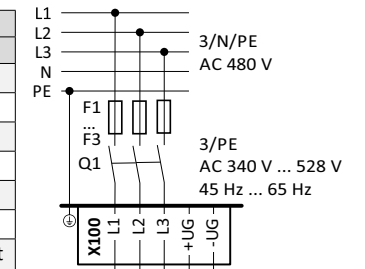
Motor connection



Terminal data, 3-phase 480 V

| Inverter | [kW] | I55AxxxF 30 ... 45 | I55AxxxF 55 ... 75 | I55AxxxF 90 ... 132 | I55AxxxF 30 ... 75 | I55AxxxF 90 ... 132 | I55AxxxF 30 ... 45 | I55AxxxF 55 ... 75 | I55AxxxF 90 ... 132 |
|--------------------------|-----------------|-----------------------|-----------------------|------------------------|-----------------------|------------------------|-----------------------|-----------------------|------------------------|
| Connection | | Mains connection X100 | | | PE connection | | Motor connection X105 | | |
| Connection type | | Screw terminal | | | PE screw | PE bolt | Screw terminal | | |
| Min. cable cross-section | mm ² | 1 | | | 1.5 | | 1 | | |
| Max. cable cross-section | mm ² | 50 | 95 | 150 | 25 | 150 | 50 | 95 | 150 |
| Stripping length | mm | 19 | 22 | 28 | 16 | - | 19 | 22 | 28 |
| Tightening torque | Nm | 4 | 10 | 18 | 4 | 10 | 4 | 10 | 18 |
| Tools required | | Hexagon socket 5 | Hexagon socket 6 | Hexagon socket 8 | PZ2 | Wrench size 13 | Hexagon socket 5 | Hexagon socket 6 | Hexagon socket 8 |

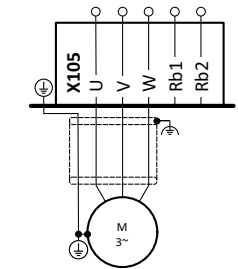
Mains connection



Fusing data

| Inverter | [kW] | 30 | 37 | 45 | 55 | 75 | 90 | 110 | 132 | |
|---|------|------------------|------|------|------|-----|-----|-----|-----|--|
| Rated output current (8 kHz) (Heavy Duty) | A | 52 | 65 | 77 | 96 | 124 | 156 | 180 | - | |
| Max. output current (15 s) | A | 78 | 98 | 116 | 144 | 186 | 234 | 270 | - | |
| Rated output current (Light Duty) | A | 48.5 | 62.4 | 78 | 92.4 | 115 | 149 | 187 | 216 | |
| Max. output current (15 s) | A | 61 | 78 | 98 | 116 | 144 | 186 | 234 | 270 | |
| Operation with mains choke | | | | | | | | | | |
| Rated mains current | A | 45.7 | 57 | 66.7 | 83 | 113 | 146 | 168 | - | |
| Fuse | | gG/gL or gRL | | | | | gR | | | |
| Max. rated current | A | 80 | 100 | 125 | 160 | 160 | 300 | 300 | 300 | |
| Circuit breaker | | | | | | | | | | |
| Characteristic | | B | | | | | | | | |
| Max. rated current | A | 80 | 100 | 125 | - | - | - | - | - | |
| Earth-leakage circuit breaker | | | | | | | | | | |
| 3-phase mains connection | | ≥ 300 mA, type B | | | | | | | | |

Motor connection



In case of Light Duty above 15 kW and Heavy Duty above 30 kW, a mains choke must be used.

6 Initial switch-on



DANGER

Electrical voltage

Incorrect wiring can cause unexpected states during the commissioning phase.

- ▶ Wiring must be complete and correct.
- ▶ Wiring must be free of short circuits and earth faults.
- ▶ The motor circuit configuration (star/delta) must be adapted to the inverter.
- ▶ The motor must be connected in-phase (rotating direction).
- ▶ The "emergency off" function of the overall system must operate correctly.
- ▶ Clear hazardous area.
- ▶ Observe safety instructions and safety clearances.

Preconditions

- The power connections must be wired.
- The digital inputs X3/DI1 (start/stop), X3/DI3 (reversal) and X3/DI4 (frequency preset 20 Hz) must be wired.
- The analog input X3/AI1 must not be wired or connected to GND.

Switch on mains voltage

- ▶ Switch on mains voltage and check readiness for operation.

Observe LED status displays "RDY" and "ERR" on the inverter front panel.

See „LED status“.  30

7 Commissioning



DANGER

Electrical voltage

Incorrect wiring can cause unexpected states during the commissioning phase.

- ▶ Wiring must be complete and correct.
- ▶ Wiring must be free of short circuits and earth faults.
- ▶ The motor circuit configuration (star/delta) must be adapted to the inverter.
- ▶ The motor must be connected in-phase (rotating direction).
- ▶ The "emergency off" function of the overall system must operate correctly.
- ▶ Clear hazardous area.
- ▶ Observe safety instructions and safety clearances.

7.1 Keypad module

- ▶ Plug the keypad onto the inverter.

The keypad can also be connected and removed during operation.



7.1.1 Functions of the keys

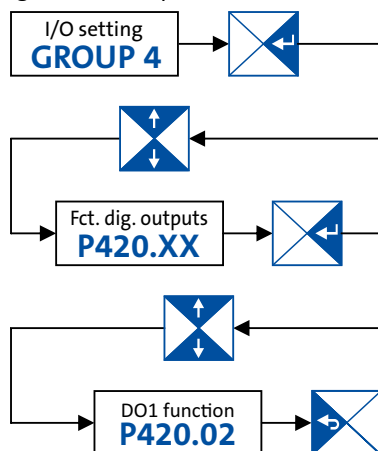
| Key | Actuation | Action |
|-----|-----------------------|---|
| | Press briefly | <ul style="list-style-type: none"> Navigation in the menu Parameter alteration |
| | Press briefly | <ul style="list-style-type: none"> Go to Menu/Parameters Confirm parameter |
| | Press and hold for 3s | <ul style="list-style-type: none"> Save parameters "P.SAVED" in the display indicates that the parameters have been saved |
| | Press briefly | Quit Menu/Parameters |
| | Press briefly | Activate keypad control |
| | Press briefly | Start motor |
| | Press briefly | Change rotating direction |
| | Press briefly | Stop motor |

The motor must be at standstill before parameters can be changed or confirmed.

The settings are saved temporarily until the motor is switched off again. To save the settings permanently, press and hold the key for 3 s.

7.1.2 Example of the keypad handling

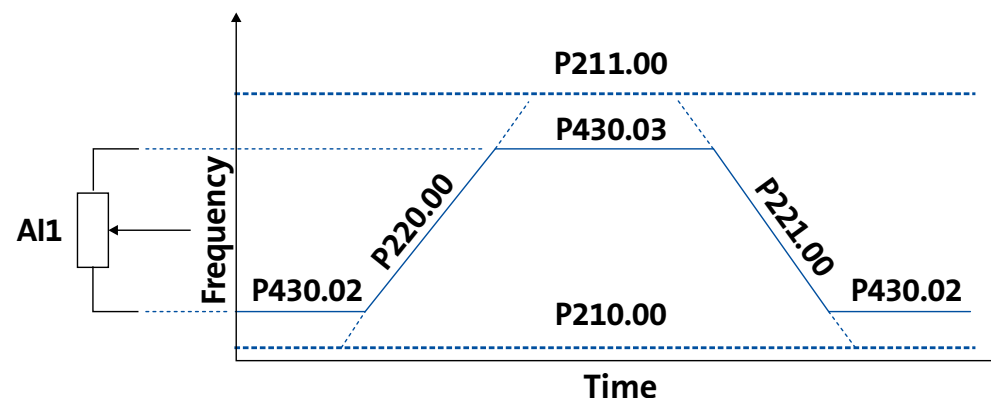
Example for DO1 function assignment with parameter **P420.02**.



7.1.3 Quick commissioning - terminal control

The following quick overview with graphical parameter representation is sufficient for commissioning many applications with terminal control. Further setting options are described in this document or in the commissioning document.

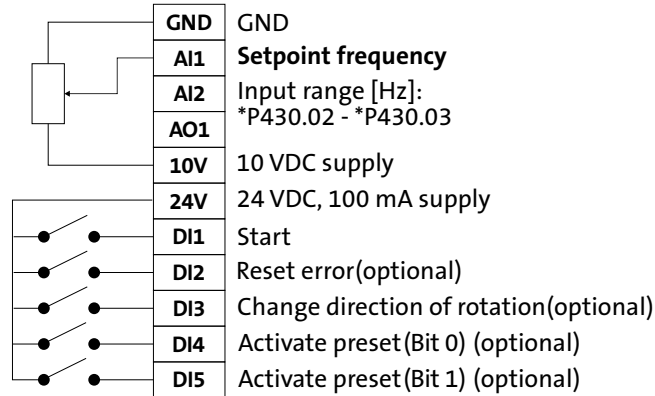
- Load default setting = Set **P700.01** to 1.
- Set the following parameters for V/f characteristic control:
 - Mains voltage **P208.01**
 - V/f characteristic data: Base voltage **P303.01**
 - V/f characteristic data: Base frequency **P303.02**
 - Minimum frequency **P210.00**
 - Maximum frequency **P211.00**
 - Acceleration time 1 **P220.00**
 - Deceleration time 1 **P221.00**
 - Analog input 1: Min frequency value **P430.02**
 - Analog input 1: Max frequency value **P430.03**
- Press and hold the key longer than 3 seconds in order to save the settings.



Commissioning

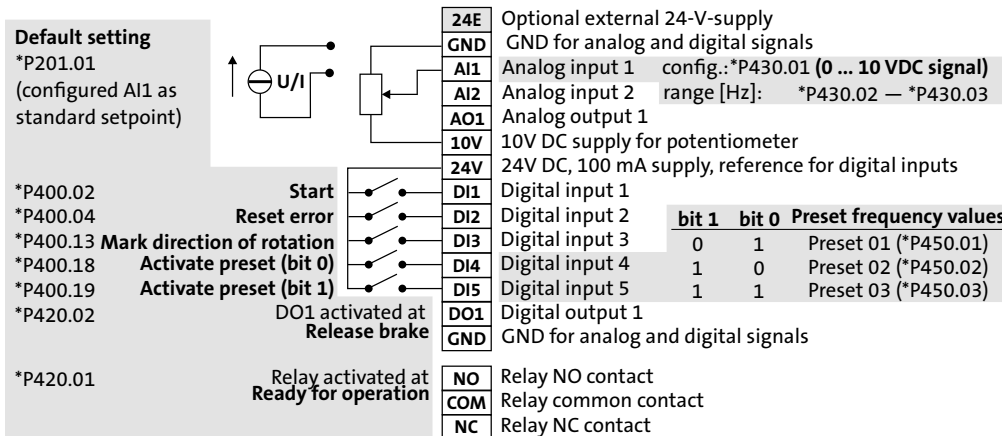
With the wiring shown below, the inverter can be operated using the control terminals (X3).

- Preset 1 is activated if DI4 is connected.
- Preset 2 is activated if DI5 is connected.
- Preset 3 is activated if DI4 and DI5 are connected at the same time.



7.1.4 Extended terminal control

The following illustration shows a more extensive wiring of the control terminals (X3) linked with the respective parameters.



7.2 Keypad control

Activate temporary keypad control

1. Press the key to activate the keypad control.
2. Press the key to confirm the keypad control.

Deactivate temporary keypad control

1. Press the key to deactivate the keypad control.
2. Press the key to confirm the keypad control.

Activate permanent keypad control

If the keypad does not have a key, the motor control is activated via the following parameters:

- ▶ Set parameter **P200.00** to **1**.
- ▶ Set parameter **P201.01** to **1**.
- ▶ Set parameter **P400.01** to **1**.
- ▶ Set parameter **P400.02** to **1**.

Use the key to start the motor.

Start/control/stop motor with keypad

1. Press the key to start the motor.
 - The keypad shows the motor speed.
2. Use the key or the key to change the frequency setpoint.
3. Press the key to stop the motor.

Change rotating direction

1. Press the key.
2. Press the key to confirm the reversal of rotating direction.

7.3 Commissioning with the EASY Starter

Commissioning and diagnostics can be carried out with the EASY starter engineering tool. A USB module and a standard USB cable (A plug to micro-B plug) is required for this. <http://www.Lenze.com>

7.4 The most important parameters at a glance

This chapter contains the most important parameters and selections. You can find a detailed description in the commissioning document. <http://www.Lenze.com>

The parameters are divided into the following function groups:

- Pxxx.xx group 0: Favorites
- P1xx.xx group 1: Diagnostics
- P2xx.xx group 2: Basic setting
- P3xx.xx group 3: Motor control
- P4xx.xx group 4: I/O setting
- P5xx.xx group 5: Network setting
- P6xx.xx group 6: Process controller
- P7xx.xx group 7: Additional functions
- P8xx.xx group 8: Sequencer

7.4.1 Group 0: Favorites

Group 0 contains the configurable favorites that are also contained in the groups 1 to 8. In the default setting these are the most common parameters for the solution of typical applications.

| Display code | Designation | Possible settings/value ranges | Keypad code | Information |
|--------------|-------------------|--------------------------------|---------------|--|
| P100.00 | Output frequency | x.x Hz (read only) | | Display of the actual output frequency. |
| P103.00 | Current actual | x.x % (read only) | | Display of the actual motor current. |
| P106.00 | Motor voltage | x VAC (read only) | | Display of the actual motor voltage. |
| P150.00 | Error code | - (read only) | | Error message. |
| P200.00 | Control selection | Flexible I/O | [0] | This selection enables a flexible assignment of the start, stop, and rotating direction commands with digital signal sources. |
| | | Keypad | [1] | This selection enables the motor to start exclusively via the start key of the keypad. Other signal sources for starting the motor are ignored. |
| P201.01 | F-setp.source | Keypad | [1] | The setpoint is specified locally by the keypad. |
| | | Analog input 1 | [2] | The setpoint is defined as analog signal via the analog input 1. |
| | | Analog input 2 | [3] | The setpoint is defined as analog signal via the analog input 2. |
| | | HTL input | [4] | The digital inputs DI3 and DI4 can be configured as HTL input to use an HTL encoder as setpoint encoder or define the setpoint as a reference frequency ("pulse train"). |
| | | Network | [5] | The setpoint is defined as process data object via the network. |
| | | Frequency preset 1 ... 15 | [11] ... [25] | For the setpoint selection, "preset" values can be parameterized and selected. All frequency presets are described in detail in the commissioning manual. http://www.Lenze.com |
| P203.01 | Start method | Normal | [0] | After start command, the standard ramps are active. |
| | | DC braking | [1] | After start command, the "DC braking" function is active for the time set in P704.02. |
| | | Flying restart circuit | [2] | After the start command, the flying restart circuit is active. |
| | | Premagnetization | [3] | After start command, the standard ramps are active and the premagnetization of the motor is activated. This reduces the motor current and smoothes the acceleration curve during the starting process (only relevant in the V/f motor control mode). |

| Display code | Designation | Possible settings/value ranges | Keypad code | Information |
|--------------|--------------------------|--|-------------|--|
| P203.03 | Stop method | Coasting | [0] | The motor has no torque (coasts down to standstill). |
| | | Standard ramp | [1] | The motor is brought to a standstill with the deceleration time 1 P221.00 (or deceleration time 2 P223.00 if activated). |
| | | Quick stop ramp | [2] | The motor is brought to a standstill with the deceleration time (P225.00) set for the "quick stop" function. |
| | | Switch-off positioning | [3] | Is similar to the stop method "standard ramp [1]". Depending on the actual output frequency, however, the inverter delays the beginning of the down-ramping so that the number of motor revolutions until a standstill is reached and thus the stopping position is always relatively constant. |
| P208.01 | Mains voltage | 230 Veff | [0] | Selection of the mains voltage for actuating the inverter. |
| | | 400 Veff | [1] | |
| | | 480 Veff | [2] | |
| | | 120 Veff | [3] | |
| P210.00 | Min. frequency | 0.0 ... 599.0 Hz | | Lower limit value for all frequency setpoints. |
| P211.00 | Max. frequency | Device for 50-Hz mains: 50 Hz * Device for 60-Hz mains: 60 Hz * | | Upper limit value for all frequency setpoints. |
| P220.00 | Acceleration 1 | 0.0 ... 5.0 ... 3600.0 s | | Acceleration time 1. |
| P221.00 | Deceleration 1 | 0.0 ... 5.0 ... 3600.0 s | | Deceleration time 1 |
| P300.00 | Motor ctrl mode | Servo control (SC ASM) | [2] | This control mode is used for servo control of an asynchronous motor. This motor control mode is described in the commissioning manual. http://www.Lenze.com |
| | | Sensorless control (SL PSM) | [3] | This control type is used for the sensorless control of a synchronous motor. This motor control mode is described in the commissioning manual. http://www.Lenze.com |
| | | Sensorless vector control (SLVC) | [4] | This control type is used for sensorless vector control of an asynchronous motor. For this purpose, observe the parameters P327.04 and P327.05 for identifying and calibrating the motor. |
| | | VFC open loop | [6] | This control mode is used for the speed control of an asynchronous motor via a V/f characteristic and is the simplest control mode. |
| | | V/f characteristic control (VFC closed loop) | [7] | The control mode is used for speed control of an asynchronous motor via a V/f characteristic with speed feedback. This motor control mode is described in the commissioning manual. http://www.Lenze.com |
| P302.00 | V/f characteristic shape | Linear | [0] | Linear characteristic for drives with constant load torque over the speed. |
| | | Square-law | [1] | Square-law characteristic for drives with a square-law load torque over the speed. |
| | | Eco | [3] | Linear characteristic with energy optimization in the partial load operational range. |
| P303.01 | Base voltage | 0 ... 230 ... 5000 V * | | Base voltage and base frequency define the V/f ratio and thus the gradient of the V/f characteristic. <ul style="list-style-type: none"> The V/f base voltage is usually set to the rated motor voltage. The V/f base frequency is usually set to the rated motor frequency. |
| P303.02 | Base frequency | Device for 50-Hz mains: 50 Hz * Device for 60-Hz mains: 60 Hz * | | Base voltage and base frequency define the V/f ratio and thus the gradient of the V/f characteristic. <ul style="list-style-type: none"> The V/f base voltage is usually set to the rated motor voltage. The V/f base frequency is usually set to the rated motor frequency. |
| P304.00 | Limitation of rotation | Only clockwise (CW) | [0] | The motor can only be rotated clockwise (CW). The transfer of negative frequency and PID setpoints to the motor control is prevented. |
| | | Both rotation directions | [1] | Both directions of motor rotation are enabled. |
| P305.00 | Switching frequency | 8 kHz var/opt/4 * | | Selection of the inverter switching frequency. |
| P306.01 | Overload selection | Heavy duty | [0] | Load characteristic for high dynamic requirements. |
| | | Light duty | [1] | Load characteristic for low dynamic requirements. |
| P308.01 | Max. load for 60s | 30 ... 150 ... 200 % | | Maximum permissible thermal motor utilization (max. permissible motor current for 60 seconds). With regard to rated motor current (P323.00) |
| P316.01 | Fixed V/f boost | 0.0 ... 2.5 ... 20.0 % * | | Constant voltage boost for the V/f characteristic control without feedback. |

| Display code | Designation | Possible settings/value ranges | Keypad code | Information |
|--------------|-------------------|---------------------------------|-------------|--|
| P323.00 | Motor current | 0.001 ... 1.700 ... 500.000 A * | | Setting of the rated motor current according to motor nameplate. |
| P324.00 | Max current | 0.0 ... 200.0 ... 3000.0 % | | Maximum overload current of the inverter. |
| P400.01 | Inverter enable | TRUE | [1] | Assignment of a trigger to the “inverter enable” function. Trigger = TRUE: The inverter is enabled (unless there is another cause for inverter disable). Trigger = FALSE: The inverter is disabled. The motor has no torque and coasts. |
| P400.02 | Run | Digital input 1 | [11] | Assignment of a trigger to the “Run” function. Function 1: Start / stop motor (default setting) Function 1 is active if no further start commands (start forward/start reverse) have been connected to triggers, no keypad control is active and no network control is active. Trigger = TRUE Let motor rotate forward (CW). Trigger = FALSE: Stop motor according to stop function (P203.03). Function 2: Start enable/stop motor Function 2 is active if further start commands have been connected to triggers, the keypad control is active or the network control is active. Trigger = TRUE: Start commands of the active control source are enabled. Trigger = FALSE: Stop motor. |
| P400.03 | Quick stop | Not connected | [0] | Assignment of a trigger to the “Activate quick stop” function. Trigger = TRUE: Activate quick stop. Quick stop ramp P225.00. Trigger = FALSE: Deactivate quick stop |
| P400.04 | Error reset | Digital input 2 | [12] | Assignment of a trigger to the “Reset error” function. Trigger = FALSE > TRUE (edge): Active error is reset (acknowledged) if the error condition is not active anymore and the error is resettable. Trigger = FALSE: No action. |
| P400.05 | DC braking | Not connected | [0] | Assignment of a trigger to the “Activate DC braking” function. Trigger = TRUE: Activate DC braking. Trigger = FALSE: Deactivate DC braking. |
| P400.06 | Start forward | Not connected | [0] | Assignment of a trigger to the “Start forward (CW)” function. Trigger = FALSE > TRUE (edge): Let motor rotate forward. Trigger = TRUE > FALSE (edge): No action. Stop via P400.01 (default setting of digital input 1). |
| P400.07 | Start reverse | Not connected | [0] | Assignment of a trigger to the “Start reverse (CCW)” function. Trigger = FALSE > TRUE (edge): Let motor rotate backward. Trigger = TRUE > FALSE (edge): No action. Stop via P400.01 (default setting of digital input 1). |
| P400.08 | Run forward | Not connected | [0] | Assignment of a trigger to the “Run forward (CW)” function. Trigger = TRUE: Let motor rotate forward. Trigger = FALSE: Stop motor. Stop via P400.01 (default setting of digital input 1). |
| P400.09 | Run reverse | Not connected | [0] | Assignment of a trigger to the “Run reverse (CCW)” function. Trigger = TRUE: Let motor rotate backward. Trigger = FALSE: Stop motor. Stop via P400.01 (default setting of digital input 1). |
| P400.13 | Reverse rot. dir. | Digital input 3 | [13] | Assignment of a trigger to the “Reverse rotating direction” function. Trigger = TRUE: The setpoint specified is inverted (i.e. the sign is inverted). Trigger = FALSE: No action / deactivate function again. |

| Display code | Designation | Possible settings/value ranges | Keypad code | Information |
|--------------|-----------------|---------------------------------------|-------------|---|
| P400.18 | Setp: Preset B0 | Digital input 4 | [14] | Assignment of a trigger to the "Activate preset (bit 0)" function. Bit with the valency 20 for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1". |
| P400.19 | Setp: Preset B1 | Digital input 5 | [15] | Assignment of a trigger to the "Activate preset (bit 1)" function. Bit with the valency 21 for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1". |
| P400.20 | Setp: Preset B2 | Not connected | [0] | Assignment of a trigger to the "Activate preset (bit 2)" function. Bit with the valency 22 for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1". |
| P420.01 | Relay function | Running | [50] | TRUE if inverter and start are enabled and output frequency > 0.2 Hz. Otherwise FALSE. |
| | | Ready for operation | [51] | TRUE if inverter is ready for operation (no error active, no STO active and DC-bus voltage ok). Otherwise FALSE. |
| | | Operation enabled | [52] | TRUE if inverter and start are enabled. Otherwise FALSE. |
| | | Stop active | [53] | TRUE if inverter is enabled and motor is not started and output frequency = 0. |
| | | Error active | [56] | TRUE if error is active. Otherwise FALSE. |
| | | Device warning active | [58] | TRUE if warning is active. Otherwise FALSE. |
| P420.02 | DO1 function | Release brake | [115] | Assignment of a trigger to digital output 1. Trigger = FALSE: X3/DO1 set to LOW level. Trigger = TRUE: X3/DO1 set to HIGH level. |
| P430.01 | AI1 input area | 0 ... 10 V DC | [0] | Definition of the input range. |
| | | 0 ... 5 V DC | [1] | |
| | | 2 ... 10 V DC | [2] | |
| | | -10 ... +10 V DC | [3] | |
| | | 4 ... 20 mA | [4] | |
| | | 0 ... 20 mA | [5] | |
| P430.02 | AI1 freq @ min | - 1000.0 ... 0.0 ... 1000.0 Hz | | Definition of the setting range for AI1. <ul style="list-style-type: none"> Rotating direction according to sign. The standard setpoint source for operating mode is selected in P201.01. |
| P430.03 | AI1 freq @ max | 50.0 Hz * 60.0 Hz * | | Definition of the setting range for "MS: Velocity mode". <ul style="list-style-type: none"> Rotating direction according to sign. The standard setpoint source for operating mode is selected in P201.01. |
| P440.01 | AO1 output area | Inhibited | [0] | Definition of the output range. |
| | | 0 ... 10 V DC | [1] | |
| | | 0 ... 5 V DC | [2] | |
| | | 2 ... 10 V DC | [3] | |
| | | 4 ... 20 mA | [4] | |
| | | 0 ... 20 mA | [5] | |

| Display code | Designation | Possible settings/value ranges | Keypad code | Information |
|--|-----------------|---|-------------|--|
| P440.02 | AO1 function | Output frequency | [1] | Actual output frequency (resolution: 0.1 Hz). |
| | | Frequency setpoint | [2] | Actual frequency setpoint (resolution: 0.1 Hz). |
| | | Analog input 1 | [3] | Input signal of analog input 1 (resolution: 0.1 %). |
| P440.03 | AO1 min. Signal | -2147483648 ... 0 ... 2147483647 | | Definition of the signal value that corresponds to the minimum value at analog output 1. |
| P440.04 | AO1 max. signal | -2147483648 ... 1000 ... 2147483647 | | Definition of the signal value that corresponds to the maximum value at analog output 1. |
| P450.01 | Freq. preset 1 | 0.0 ... 20.0 ... 599.0 Hz | | Parameterizable frequency setpoints (preset 1). |
| P450.02 | Freq. preset 2 | 0.0 ... 40.0 ... 599.0 Hz | | Parameterizable frequency setpoints (preset 2). |
| P450.03 | Freq. preset 3 | 0.0 ... 50.0 – 40.0 ... 599.0 Hz * | | Parameterizable frequency setpoints (preset 3). |
| P450.04 | Freq. preset 4 | 0.0 ... 0.0 ... 599.0 Hz | | Parameterizable frequency setpoints (preset 4). |
| * Default setting dependent on the model | | | | |

7.4.2 Group 2: Basic setting

| Display code | Designation | Possible settings | Keypad code | Information |
|--------------|------------------------------|-------------------|-------------|--|
| P225.00 | Quick stop deceleration time | 1.0 s | | Quick stop deceleration time for "MS: Velocity mode" <ul style="list-style-type: none"> If the "Quick stop" function is activated, the motor is brought to a standstill within the deceleration time set here. The deceleration time set refers to the deceleration from the maximum frequency set (P211.00) to standstill. In the case of a lower actual frequency, the actual deceleration time is reduced accordingly. Setting is not effective in the operating mode P301.00 = "CiA:Velocity mode". |

7.4.3 Group 3: Motor control

| Display code | Designation | Possible settings | Keypad code | Information |
|--------------|--------------------------------------|--------------------|-------------|--|
| P320.04 | Rated speed | 50 ... 50000 rpm | | General motor data. |
| P320.05 | Rated frequency | 1.0 ... 10000.0 Hz | | Carry out settings as specified by motor nameplate data. |
| P320.06 | Rated power | 0.00 ... 655.35 kW | | Note! |
| P320.07 | Rated voltage | 0 ... 65535 V | | When you enter the motor nameplate data, take into account the phase connection implemented for the motor (star or delta connection). Only enter the data applying to the connection type selected. |
| P320.08 | Cos phi | 0.00 ... 1.00 | | |
| P327.04 | Identify motor data | 0 ... 1 | | 1 = start automatic identification of the motor data. <ul style="list-style-type: none"> Inverter characteristics, motor equivalent circuit diagram data and controller settings are identified and set automatically. During the procedure, the motor is energized! |
| P327.05 | Calibrate motor data (non-energized) | 0 ... 1 | | 1 = start automatic calibration of the motor data. <ul style="list-style-type: none"> A default inverter characteristic is loaded. The motor equivalent circuit diagram data and controller settings are calculated on the basis of the currently set rated motor data. The motor is not energized. |

7.4.4 Group 7: Additional functions

| Display code | Designation | Possible settings | Keypad code | Information |
|-------------------------------|---|-------------------|-------------|---|
| P700.01 | Device commands: Load default settings | Off / ready | [0] | Only status feedback |
| | | On / start | [1] | 1 = reset all parameters in the RAM memory of the inverter to the default setting that is stored in the inverter firmware. <ul style="list-style-type: none"> All parameter changes made by the user are lost during this process! This process may take some seconds. When the device command has been executed successfully, the value 0 is shown. Loading parameters has a direct effect on cyclic communication: The data exchange for control is interrupted and a communication error is generated. |
| P700.03 | Save USER data | Off / ready | [0] | 1 = save current parameter settings in the user memory of the memory module with mains failure protection. <ul style="list-style-type: none"> It may take some seconds to execute the task. When the device command has been executed successfully, the value 0 is shown. Do not switch off the supply voltage during the saving process and do not unplug the memory module from the inverter! When the inverter is switched on, all parameters are automatically loaded from the user memory of the memory module to the RAM memory of the inverter. |
| | | On / start | [1] | |
| | | In progress | [2] | |
| | | Action cancelled | [3] | |
| | | No access | [4] | |
| No access (Inverter disabled) | [5] | | | |

8 Troubleshooting

8.1 Error message

If an error is pending, the keypad shows the following information.

| | | |
|--|----------------|-------------|
| <p>The keypad display shows the text 'Warn. DC Bus UV' in the top line and 'W3221' in the bottom line. Callout 1 points to the top line, callout 2 points to the 'W' character, and callout 3 points to the '3221' characters. Below the display are buttons labeled 'REM', 'AUTO', and 'SET'.</p> | 1 = error text | |
| | 2 = error type | F = fault |
| | | T = trouble |
| | | W = warning |
| 3 = error code (hexadecimal) | | |
| Faults (F) and trouble (T) are displayed continuously. The inverter is disabled. | | |
| Warnings (W) are displayed every 2 seconds for a short time. The inverter is probably disabled. | | |

8.2 Reset error

Reset error via keypad

Errors can be reset via the key if the cause of the error has been eliminated and no blocking time is active.

- ▶ Press the key to reset the error. The motor is stopped.
- ▶ Press the key to reset the stop.


Reset error via terminal control

When terminal control is used, errors can be reset in 2 ways:












1. Via start signal **P400.02** (default setting of digital input 1).
 - Cause of error has been eliminated and no blocking time is active.
 - The signal at the digital input 1 (**P400.02**) must drop and then be applied again.
2. Via **P400.04** (default setting of digital input 2).
 - Cause of error has been eliminated and no blocking time is active.
 - The error is reset if a signal is applied to digital input 2 (**P400.04**).

8.3 Error codes

| Error code | Description | Classification | Remedy | Blocking time [s] | Reset possible |
|------------|--|----------------|---|-------------------|----------------|
| 2250 | CiA: Continuous overcurrent (inside the device) | Fault | <ul style="list-style-type: none"> • Check motor and wiring for short circuit. • Check brake resistor and wiring. • Check motor circuit (delta connection, star connection). • Check setting of the motor data. | 5 | Yes |
| 2320 | Short circuit or earth leakage on the motor side | Fault | <ul style="list-style-type: none"> • Check motor cable. • Check the length of the motor cable. • Use shorter or lower-capacitance motor cable. | 5 | Yes |
| 2340 | CiA: Short circuit (inside the device) | Fault | <ul style="list-style-type: none"> • Check motor cable for short circuit. | 5 | Yes |
| 2350 | CiA: $i^2 \cdot t$ overload (thermal state) | Fault | <ul style="list-style-type: none"> • Check drive sizing. • Check machine/driven mechanics for excessive load. • Check setting of the motor data. • Reduce values for slip compensation (P315.01, P315.02) and oscillation damping (P318.01, P318.02). | 5 | Yes |
| 2382 | Error: Device utilisation (lxt) too high | Fault | <ul style="list-style-type: none"> • Check drive sizing. • Reduce maximum overload current of the inverter (P324.00). • In case of high mass inertias, reduce maximum overload current of the inverter (P324.00) to 150 %. | 3 | Yes |
| 2383 | Warning: Device utilisation (lxt) too high | Warning | <ul style="list-style-type: none"> • Check drive sizing. | 0 | Yes |
| 3120 | Mains phase fault | Fault | <ul style="list-style-type: none"> • Check wiring of the mains connection • Check fuses. | 0 | Yes |
| 3210 | DC bus overvoltage | Fault | <ul style="list-style-type: none"> • Reduce dynamic performance of the load profile. • Check mains voltage. • Check settings for braking energy management. • Connect brake resistor to the power unit and activate the integrated brake chopper. (P706.01 = 0: brake resistance). | 0 | Yes |
| 3211 | Warning: DC bus overvoltage | Warning | <ul style="list-style-type: none"> • Reduce dynamic performance of the load profile. • Check mains voltage. • Check settings for braking energy management. • Connect brake resistor to the power unit and activate the integrated brake chopper. (P706.01 = 0: brake resistance). | 0 | Yes |
| 3220 | DC bus undervoltage | Trouble | <ul style="list-style-type: none"> • Check mains voltage. • Check fuses. • Check DC-bus voltage (P105.00). • Check mains settings. | 0 | Yes |
| 3221 | Warning: DC bus undervoltage | Warning | <ul style="list-style-type: none"> • Check mains voltage. • Check fuses. • Check DC-bus voltage. • Check mains settings. | 0 | Yes |
| 3222 | DC-bus voltage too low for switch-on | Warning | <ul style="list-style-type: none"> • Check mains voltage. • Check fuses. • Check mains settings. | 0 | Yes |
| 4210 | PU: Overtemperature fault | Fault | <ul style="list-style-type: none"> • Check mains voltage. • Provide for a sufficient cooling of the device (display of the heatsink temperature in P117.01). • Clean fan and ventilation slots. If required, replace fan. • Reduce switching frequency (P305.00). | 0 | Yes |
| 4281 | Heatsink fan warning | Warning | <ul style="list-style-type: none"> • Clean fan and ventilation slots. If required, replace fan. The fans can be unlocked via locking hooks and can then be removed. | 0 | Yes |
| 4310 | Error: Motor overtemperature | Fault | <ul style="list-style-type: none"> • Check drive sizing. • Check motor temperature sensor and wiring (X109/T1 and X109/T2). | 5 | Yes |

| Error code | Description | Classification | Remedy | Blocking time [s] | Reset possible |
|------------|---|----------------|--|-------------------|----------------|
| 5112 | 24 V supply fault | Warning | <ul style="list-style-type: none"> Check optional external 24V voltage supply (terminal X3/24E), if connected. Check mains voltage. | 0 | Yes |
| 5180 | 24-V supply overload | Warning | <ul style="list-style-type: none"> Check 24-V output and digital outputs for earth fault or overload. | 0 | Yes |
| 6280 | Trigger/functions connected incorrectly | Trouble | <ul style="list-style-type: none"> Check and correct the assignment of the triggers to the functions. With keypad or network control, the two functions "Inverter enable" (P400.01) and "Run" (P400.02) can also be set to "Constant TRUE [1]" to start the motor. | 0 | Yes |
| 7180 | Motor overcurrent | Fault | <ul style="list-style-type: none"> Check motor load. • Check drive sizing. Adapt the set error threshold (P353.01). | 1 | Yes |
| 9080 | Keypad removed | Fault | <ul style="list-style-type: none"> Plug on the keypad again or activate another control source. | 0 | Yes |
| FF02 | Error: Brake resistor overload | Fault | <ul style="list-style-type: none"> Check drive sizing. Check settings for the braking energy management. <p>Note: The error will be reset if the thermal load falls below the error threshold (P707.09) of - 20 %.</p> | 5 | Yes |
| FF06 | Motor overspeed | Fault | <ul style="list-style-type: none"> Adapt the maximum motor speed (P322.00) and the error threshold (P350.01). | 1 | Yes |
| FF36 | Warning: Brake resistor overload | Warning | <ul style="list-style-type: none"> Check drive sizing. Check settings for the braking energy management. <p>Note: The warning will be reset if the thermal load falls below the warning threshold (P707.08) of - 20 %.</p> | 0 | Yes |
| FF37 | Automatic start disabled | Fault | <ul style="list-style-type: none"> Deactivate start command and reset error. | 0 | Yes |
| FF85 | Keypad full control active | Warning | <ul style="list-style-type: none"> To exit the control mode, press the  keypad key. | 0 | Yes |

8.4 LED status

| LED "RDY" (blue) | LED "ERR" (red) | Status/meaning |
|--|---|---|
| off | off | No supply voltage. |
|  |  | Mains voltage is switched on, inverter is initialized. |
|  flashes | off | Inverter is disabled, ready for operation. |
| |  flashes | Safe torque off (STO) active, warning active. |
|  flashes | off | Inverter inhibited. |
| |  flashes fast | Inverter disabled, warning active. |
| |  | Inverter disabled, error active. |
| |  every 1.5 s on | Inverter disabled, no DC-bus voltage. |
|  | off | Inverter enabled. |
| | off | The motor rotates according to the specified setpoint or quick stop active. |
| |  flashes fast | Inverter enabled, warning active. The motor rotates according to the specified setpoint or quick stop active. |
| |  flashes | Inverter enabled, quick stop as response to fault active. |

9 Further documents

For certain tasks, information is available in further documents.

| Document | Contents/topics |
|---------------------------|---|
| Project Planning document | Fundamental information on project planning and ordering the product |
| Commissioning document | Fundamental information for the installation and commissioning of the product |
| Mounting instructions | Fundamental information on mounting the product |

The documents can be found in the [Lenze Doc Finder](#).

10 Disposal

If pollutants are disposed off improperly, they may cause a lasting damage to human health and the environment. Thus, electrical and electronic equipment must be collected separately from unsorted municipal waste so that it may be recycled or disposed of properly.

If available, put the components to the company internal disposal from where it is passed on to specialized waste management companies.

It is also possible to return the components to the manufacturer. For this purpose, please contact the customer service of the manufacturer.

More detailed information on disposal can be obtained from the corresponding specialist firms and the competent authorities.

The packaging of the component must be disposed of separately. Paper, cardboard and plastics must be recycled.

11 Glossary

| Abbreviation | Meaning |
|--------------|---|
| AIE | Error acknowledgement ("Acknowledge In Error") |
| OFF state | Signal status of the safety sensor when it triggers or responds |
| QSP | Quick stop |

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