Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS

Motor type : 1AV3073B **INNOMOTICS GP - 71 M - IM B35 - 4p**

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	η 3) 4/4	η 3) 3/4	η 3) 2/4	cosφ 3) 4/4	cosφ 3) 3/4	cosφ 3) 2/4	I_A/I_N I_I/I_N	M_A/M_N T_I/T_N	M_K/M_N T_B/T_N	IE-CL
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	0.37	-/-	1.72	1410	2.5	77.3	76.8	73.2	0.70	0.61	0.48	4.8	3.1	3.1	IE3
400	Y	50	0.37	-/-	0.99	1410	2.5	77.3	76.8	73.2	0.70	0.61	0.48	4.8	3.1	3.1	IE3
460	Y	60	0.43	-/-	0.99	1710	2.4	78.2	77.5	74.1	0.70	0.61	0.49	5.1	3.0	3.1	IE3
460	Y	60	0.37	-/-	0.90	1720	2.0	78.2	76.9	72.5	0.66	0.57	0.45	5.7	3.6	3.8	IE3

IM B35 / IM 2001		FS 71 M		IP55	UKCA	IEC/EN 60034	IEC, DIN, ISO, VDE, EN				

Environmental conditions : -20 °C - +40 °C / 1000 m	Locked rotor time (hot / cold) : 47.50 s | 55.70 s

Mechanical data

Sound level (SPL / SWL) at 50Hz|60Hz	56.0 / 67.0 dB(A) 2) 3)	62.0 / 73.0 dB(A) 2) 3)
Moment of inertia	0.0014 kg m²	
Bearing DE | NDE	6202 2Z C3	6202 2Z C3
bearing lifetime		
L_{10mh} $F_{Rad\ min}$ for coupling operation 50|60Hz 1)	40000 h	32000 h
Regreasing device	Without	
Grease nipple	-/-	
Type of bearing	Preloaded bearing DE	
Condensate drainage holes	Without	
External earthing terminal	Without	

Vibration severity grade	A
Thermal class	F
Duty type	S1
Direction of rotation	bidirectional
Frame material	aluminum
Net weight of the motor (IM B3)	9 kg
Coating (paint finish)	Standard paint finish C2
Color, paint shade	RAL7030
Motor protection	(B) 1 PTC thermistor - for tripping (2 terminals)
Method of cooling	IC411 - self ventilated, surface cooled
Carbon footprint (without options)	50kg

Terminal box

Terminal box position	top
Material of terminal box	Aluminium
Type of terminal box	TB1 B00
Contact screw thread	6xM4
Max. cross-sectional area	4.0 mm²

Main cable entry	1xM25x1.5
Main cable gland	1 plug
Auxiliary cable entry	1xM16x1.5
Auxiliary cable gland	1 plug

I_A/I_N = locked rotor current / current nominal
M_A/M_N = locked rotor torque / torque nominal
M_K/M_N = break down torque / nominal torque

1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power / at full load

3) Value is valid only for DOL operation with motor design IC411

Responsible department	Technical reference	Created by	Approved by	
IN LVM		IPC		***Technical data are subject to change! There may be discrepancies between calculated and rating plate values.***

Link documents

INNOMOTICS

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